

# CCS Technical Documentation

## RH-12/RH-28 Series Transceivers

# 7 – System Module

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## Glossary of Terms

ACI	Accessory Control Interface
ADC	Analog Digital Connector
AMSL	After Market Service Leader
ASIC	Application Specific Integrated Circuit
ASIP	Application Specific Integrated Passive
ADSP	Application DSP (expected to run high level tasks)
ARM	Advanced RISC Machines
BB	Baseband
BC02	Bluetooth module made by CSR
CCP	Compact Camera Port
CDSP	Cellular DSP (expected to run low level tasks)
COF	Chip on foil
COG	Chip On Glass
CSR	Cambridge Silicon Radio
CSTN	Color Super Twisted Nematic
CTSI	Clock Timing Sleep and Interrupt block of Tiku
DCT4.5	Digital Core Technology, generation 4.5
DSP	Digital Signal Processor
EMC	Electro Magnetic Compatibility
ESD	Electro Static Discharge
FCI	Functional Cover Interface
FR	Full Rate
FSTN	Film compensated Super Twisted Nematic

GSM	Global System Mobile
HW	Hardware
IF	Interface
IHF	Integrated Hands Free
IMEI	International Mobile Equipment Identity
IR	Infrared
IrDa	Infrared Data Association
LCD	Liquid Crystal Display
LDO	Low Drop Out
LED	Light Emitting Diode
LPRF	Low Power Radio Frequency
MCU	Microprocessor Control Unit
NTC	Negative temperature Coefficient, temperature sensitive resistor used as an temperature sensor.
PA	Power Amplifier (RF)
PDA	Personal Digital Assistant
PDRAM	Program/Data RAM (on chip in Tiku)
Phoenix	SW tool of DCT4.x
PUP	General Purpose IO (PIO), USARTS and Pulse Width Modulators
PWB	Printed Wired Board
PopPort™	BB4.x system connector. It includes: USB, Stereo headset, Fbus.
RTC	Real Time Clock, small circuitry that keeps track of updating the clock counter and the calendar. To keep it update without (or empty) battery, an alternative power source can be used: small battery or large capacitor.
SARAM	Single Access RAM

SIM	Subscriber Identification Module
SW	Software
SWIM	Subscriber / Wallet Identification Module
SPR	Standard Product Requirements
STI	Serial Trace Interface
TCXO	Temperature controlled Oscillator
Tiku	Finnish for Chip, Successor of the UPP (Universal Phone Processor), Official Tiku3G
UEME	Universal Energy Management Enhanced
UI	User Interface
USB	Universal Serial Bus
UPP	Universal Phone Processor
UPP_WD2	Communicator version of DCT4 system ASIC

## Baseband Module Introduction

This chapter describes the baseband module for the RH-12/RH-28 program. The baseband module includes the baseband engine chipset, the UI components and acoustical parts of the transceiver.

The RH-12/RH-28 is a hand-portable GSM900/GSM1800/GSM1900 phone for the Smart Classic segment, having the DCT4.5 generation baseband- and RF circuitry. The key driver for this product is the implementation of EDGE, introducing true multimedia capability from WCDMA in GSM single mode.

RH-12/RH-28 is equipped with the DCT4 connector, supporting most of the DCT4 accessories. The battery interface is relative new consisting of only 3 connections. Standard battery will be the BL-5C battery with 850mAh.



## Features

The HW specific features of the RH-12/RH-28 phone:

- Monoblock phone with easy exchangeable covers.
- Tripleband Engine (900, 1800, 1900), US variant (850, 1800, 1900)
- E-GPRS MSC 5 (2+2)
- FR, EFR, AMR codecs
- Integrated Camera and Colour Display 128x128
- MMS (Multi Media Messaging), Java MIDP, SyncML & xHTML
- MMC for storing pictures and sound
- SWIM (dual function SIM)
- MP3 Player
- USB Interface to PC
- IrDA
- Bluetooth
- FM Radio
- IHF
- PopPort™ Accessory support

Accessories:

- Chargers: ACP7, ACP8, ACP9, ACP-12, LCH-8, LCH-9, LCH-12, AC-1 and DC-1.
- Car accessories: CARK126, CARK112, BHF-1 and RAN CARKIT 610/810 (BT).
- Audio accessories: HDB-4, HS-5, LPS-4, HS-10, HS-6, SU-3, HF-2, HDS-3, HDW-1, HDW-2, DT-1
- Connectivity accessories: DCV-14, DKU-2, DTL-4 and HDA-10.
- Accessory covers: X-press on covers.

## Environmental Specifications

### Normal and extreme voltages

Following voltages are assumed as normal and extreme voltages for used battery:

Table 1: Normal and extreme voltages

Voltage	Voltage [V]	Condition
<b>General Conditions</b>		
Nominal voltage	3,700	
Lower extreme voltage	3,145	1
Higher extreme voltage (fast charging)	4,230	2
<b>HW Shutdown Voltages</b>		
Vmstr+	2,1 ± 0,1	Off to on
Vmstr-	1,9 ± 0,1	On to off
<b>SW Shutdown Voltages</b>		
Sw shutdown	3,1	In call
Sw shutdown	3,2	In idle
<b>Min Operating Voltage</b>		
Vcoff+	3,1 ± 0,1	Off to on
Vcoff-	2,8 ± 0,1	On to off

<sup>1</sup> ADC settings in the SW might shutdown the phone above this value.

<sup>2</sup> During fast charging of an empty battery, the voltage might exceed this value. Voltages between 4.20 and 4.60 might appear for a short while.

### Temperature conditions

- Operational temperature range (all specifications met within this range):  
-5°C.. +55°C (stationary use)
- Functional temperature range (reduced performance):  
-30°C.. +70°C
- Storage temperature range:  
-30°C.. +85°C

Temperatures at -10°C, +25°C and +55°C are used for the cpk analysis.

The baseband module complies with the SPR4 Operating Conditions.

**Humidity**

Relative humidity range is 5...95%.

The BB module is not protected against water. Condensed or splashed water might cause malfunction. Any submerge of the phone will cause permanent damage. Long-term high humidity, with condensation, will cause permanent damage because of corrosion.

The baseband module complies with the SPR4 Operating Conditions.

**Vibration**

The baseband module complies with the SPR4 Operating Conditions.

**ESD strength**

Standard for electrostatic discharge is IEC 61000-4-2 and level 4 requirements are fulfilled.

The baseband module complies with the SPR4 Operating Conditions.

## Technical Specifications

### UEME

UEME is the Universal Energy Management Enhanced IC for digital hand portable phones. In addition to energy management, the UEME functionality performs all base-band mixed-signal functions.

The different states of the UEME are explained below.

#### No supply

In the NO\_SUPPLY mode the UEME has no supply voltage ( $V_{BAT} < V_{MSTR}$  and  $V_{BACK} < V_{BUCOFF-}$ ). This mode is due to the fact, that both the main battery and the backup battery are either disconnected or both discharged to a low voltage level.

The UEME will recover from NO\_SUPPLY into the RESET mode, if the VBAT voltage level rises above the VMSTR+ level, by either reconnecting the main battery or charging it to such level.

#### Backup

In the BACK\_UP mode the main battery is either disconnected or has a low voltage level ( $V_{BAT} < V_{MSTR-}$  and  $V_{BACK} > V_{BUCOFF+}$ ).

The regulator VRTC that supplies the real time clock is disabled in the BACK\_UP mode. Instead the unregulated backup battery voltage VBACK supplies the output of the VRTC. All other regulators are disabled and the phone has no functionality.

The UEME will recover from the BACK\_UP mode into the RESET mode if VBAT rises above VMSTR+.

#### Power off

In order for the UEME to be in the PWR\_OFF mode, it must have supply voltage ( $V_{BAT} > V_{MSTR+}$ ).

The VRTC regulator is enabled and supplying the RTC within the UEME. The UEME will enter the RESET mode after a 20 ms delay whenever one of the below listed conditions is logically true:

- The power button is activated.
- Charger connection is detected.
- RTC alarm is detected.

The UEME will enter PWR\_OFF from all other modes except NO\_SUPPLY and BACK\_UP if the internal watchdog elapses.

### Reset

When the UEME enters the RESET mode from the PWR\_OFF mode the watchdog is enabled. If the VBAT fails to rise above the power-up voltage level VCOFF+ (3.1 V), before the watchdog elapses, the UEME will enter the PWR\_OFF mode. Otherwise, after a 200 ms delay the regulator VFLASH1 will be enabled and after an additional delay of 500  $\mu$ s, the regulators VANA, VIO, VCORE and VR3 will be enabled. All other regulators i.e. VFLASH2, VSIM, VR1, VR2 and VR4 – VR7 are software controlled and disabled by default. After an additional delay of 20 ms, the UEME enters the PWR\_ON mode.

### Power on

In PWR\_ON the UEME is fully functional in the sense that all internal circuits are powered up or can be by means of software. The UEME will enter the PWR\_OFF mode if VBAT drops below VCOFF- for a period of time longer than 5  $\mu$ s. The UEME will furthermore enter the PWR\_OFF mode if either of the watchdogs Operational State Machine (approx. 100  $\mu$ s), Security (32 sec.) or Power Key (4 sec.) elapses or if any of the regulators triggers the thermal protection circuitry.

### Sleep

The UEME can be forced into the SLEEP mode by the Tiku by setting the input SLEEPX low for more than 60  $\mu$ s. This state is entered when the external Tiku activity is low (phone in sleep) and thereby lowering the internal current consumption of the UEME. The regulator VANA is disabled and VR1 – VR7 are either disabled or in low quiescent mode. From SLEEP the UEME enters PWR\_ON if SLEEPX goes high, the PWR\_OFF mode if watchdog elapses or the BACK\_UP mode if VBAT drops below VMSTR-.

### Protection mode

The UEME has two separate protection limits for over temperature conditions, one for the charging switch and one for the regulators. The temperature circuitry measures the onchip temperature. In case of charging over temperature, the circuit turns the charging switch off. In case of over temperature in any of the regulators, the UEME powers off.

## DC Characteristics

The figures in the following table reflect the specification of the voltage and current regulators within the UEME.

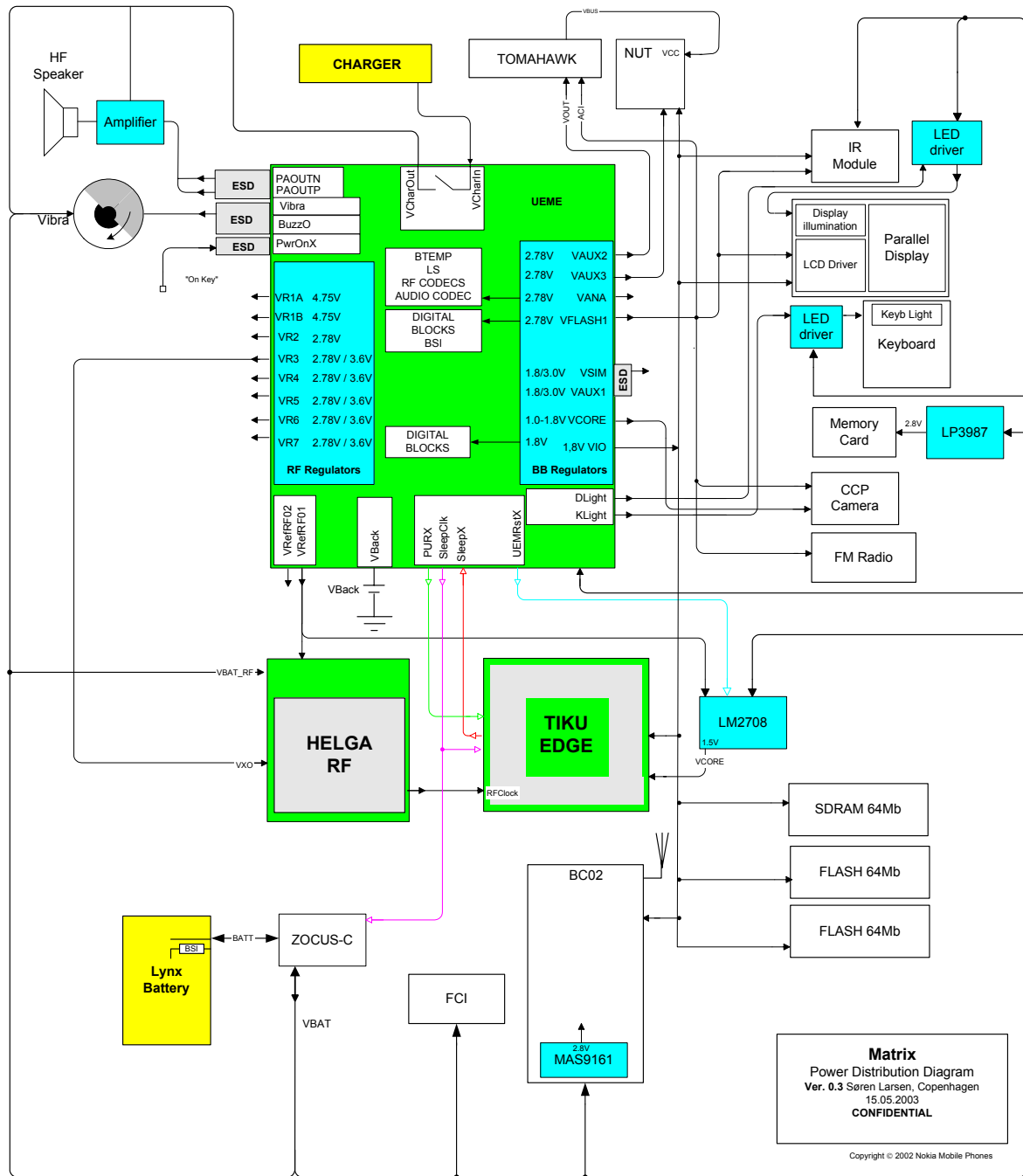
Table 2: UEME Regulator Output and State in Sleep

Name	Voltage (V)			Current (mA)		Filter	Comment
	Min	Nom	Max	Max	Sleep Max		
VANA	2.70	2.78	2.86	80		2	5uA minimum for stability. Controlled by the UEME. Disabled in Sleep mode.
VFLASH1	2.61	2.78	2.95	70	1.5	1	5uA minimum for stability. Controlled by the UEME.
VIO	1.72	1.80	1.88	150	0.5	3	5uA minimum for stability. Controlled by the UEME.
VCORE	1.41	1.50	1.59	200	0.2	1	5uA minimum for stability. MCUSW is setting the voltage.
VAUX1	1.745 2.91	1.80 3.0	1.855 3.09	50	0.5	1	Voltage level is set by MCUSW.
VAUX2	2.70	2.78	2.86	70	0.5	1	5uA minimum for stability.
VAUX3	2.70	2.78	2.86	10	0.5	1	5uA minimum for stability.
VSIM	1.745 2.91	1.80 3.00	1.855 3.09	25	0.5	-	5uA minimum for stability.
VR1A/B	4.60	4.75	4.90	10	-	4	Disabled in Sleep mode. The maximum current is for 1 regulator active. If both are used, maximum 5mA each.
VR2	2.70 (2.61)	2.78 (2.78)	2.86 (2.95)	100	-	5	100uA minimum for stability. Active during (Sleepmode).
VR3	2.70	2.78	2.86	20	-	4	100uA minimum for stability. Controlled by the UEME.
VR4	2.70	2.78	2.86	50	0.1	6	100uA minimum for stability.
VR5	2.70	2.78	2.86	50	0.1	7	100uA minimum for stability.
VR6	2.70	2.78	2.86	50	0.1	7	100uA minimum for stability.
VR7	2.70	2.78	2.86	45	-	7	100uA minimum for stability.

Power Distribution

The connection of the miscellaneous power connection can be seen in the following overview.

Figure 1: Power distribution



## Tiku

This is the main digital baseband ASIC.

### Main Features

The Tiku consists of the following sections:

- Arm 925 MPU
- A-DSP (Lead3 for Application sw – 4KB ApiRam, 128KB saram, 32KB daram)
- C-DSP (Lead3 for Cellular sw – 4KB ApiRam, 128KB saram, 32KB daram)
- DSP Co-processors (DCT and Motion Estimator) on both DSP
- Corona EDGE hardware accelerator
- Serial flash interface (SFI001)
- 2G Body logic, as in UPP-WD2
- 4Mb of pdram.
- Traffic controller for memory interface (dct4 flash/sram, sdram)
- General purpose USARTs
- SIM card interface
- 2<sup>nd</sup> SIM interface (used for MMC)
- I<sup>2</sup>C interface (used for FCI)
- GSM coder
- Interface control for: keyboard, LCD, Camera, audio and UEME control
- Accessory interfaces: IrDa and LPRF (Bluetooth)
- Handling of RF-BB interface
- I/O voltage = 1.8V, Core voltage = 1.5V
- TI 15C035 process (Tiku version 1.11)
- 288 pins uBGA, 0.5mm pitch, 12 mm x 12 mm package (Tiku version 1.11)

The Brain consists of 5 sections; the ARM925 Mega-Module, (consisting of the ARM9



MCU, Cache memory, Parallel LCD Controller, and Traffic Controller), C-DSP Lead 3 Mega-Module, A-DSP Lead 3 Mega-Module, PDRAM, and PDA Peripherals.

The ARM-Mega-Module has a Traffic controller, which provides the interface between the MCU, external memories, LCD controller, and internal busses. It also processes the data packages for memory access.

The PDA Peripherals consists of Camera Compact Port (CCP) interface, Multi-Media Card (MMC), IR, USB, and Display interfaces.

### Memory Block

For the MCU, TIKU includes ROM, 2 kbytes, that is used mainly for boot code of MCU. For the program memory, 4Mbit (256K x 16bit, organized as 8 banks of 64Kb) PDRAM is integrated. RAM is mainly for MCU purposes. The MCU can also store a code into the external flash memory, which consist of one NOR flash and one NAND flash. The size of the NOR flash is 128Mbit (8Mbit x16bit) and it's used for primary application code. The secondary flash is a NAND flash, which is used for slow accessible data such as user-settings, pictures, ringtones etc. (non speed dependent code). The size of the NAND flash is 64Mbit (4096K x 16 bit).

### Memory

The external memory interface consists of three different type of memory, used for different purposes.

#### NOR Flash

The NOR flash is used as the primary data storage. Here the MCU sw package is stored.

Furthermore, the memory is capable of handling burst mode (multiplexed address/data-bus) and memory blocking, which is controlled by TIKU.

#### NAND Flash

The NAND flash is used as the secondary data storage, mainly used for user specific data like sounds, games, pictures and other applications. This device also stores language package.

#### SDRAM

The SDRAM is used as a data handling memory.

The SDRAM interface to TIKU is different than the 24 lines multiplexed data/address bus used for the flash memory. First the address is set up then the data is latched out in a normal asynchronous/synchronous way. In the synchronous mode, the data is clocked out at a maximum frequency at 133MHz.

## Charging

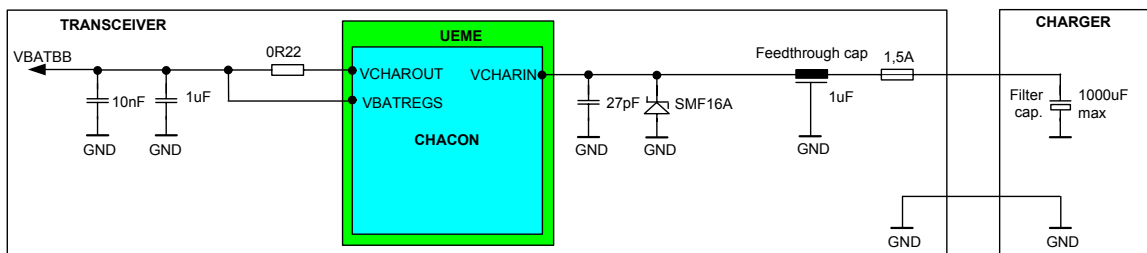
The RH-12/RH-28 program is conform to the global NMP Charger Interface.

This comprehensive interface ensures future proofing should new chargers become available.

Charging is controlled by the UEME and external components are needed for EMC, reverse polarity and transient protection of the input to the baseband module. The charger connection is through the system connector interface. The DCT4.5 baseband is designed to support DCT3 chargers from an electrical point of view. Both 2- and 3-wire type chargers are supported. 3-wire chargers are treated as 2-wire (PopPort™ specifications).

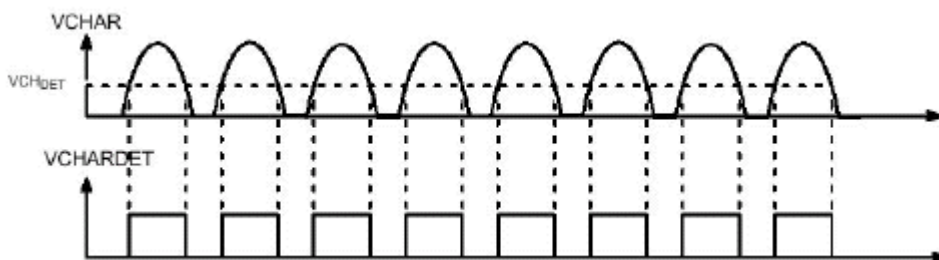
The operation of the charging circuit has been specified in such a way as to limit the power dissipation across the charge switch and to ensure safe operation in all modes.

Figure 2: Charging



Connecting a charger creates voltage on VCHAR input. When VCHAR input's voltage level is detected to rise above the VCHDET+ threshold by CHACON, the charging starts. The VCHARDET signal is generated to indicate the presence of the charger. However, detection output signal must be gated always to a logical '0' when MSTRX='0', in order not to force logical high level to the UEME's internal blocks that are not supplied at the time. Level crossing detection of the VCHAR line is used to generate synchronizing pulses for UEME's state machine for control of rectifier type chargers. The VCHARDET output gives a logical '1' when the VCHAR input is detected to be above the VCHDET+ level and '0' when the VCHAR input level is below VCHDET.

Figure 3: Detection of charger / generation of charger synchronisation pulses



In case the main battery is fully discharged and the UEME subsequently is without power, i.e. in NO\_SUPPLY or BACKUP mode, the start-up charging circuitry is in control, giving the possibility to detect a charger and engage charging. If the VBAT level is detected to be lower than the master reset voltage (VMSTR-) the CHACON will charge the battery with a constant current of 100 mA until VBAT exceeds VMSTR+. When this happens, from a charging point of view, normal PWM charging situation resumes. A PWM signal is generated by the digital part of the UEME, which sources the CHACON. The frequency of the signal can be either 1 Hz or 32 Hz. If the connected charger is of a 2-wire kind, e.g. ACP- 7, the PWM signal has the frequency of 1 Hz. If the charger on the other hand is a 3-wire type, e.g. ACP-9, the switch is left on permanently and the 32 Hz PWM control signal routed to the charger in order to produce a constant voltage.

## Battery

Type: BL-5C

Technology: Li-Ion. 4.2V charging. 3.1V cut-off

Capacity: 850 mA/h (BSI=75K)

The battery is a Li Ion based standard cell with LiMnO chemistry.

This type of battery has a three-pin connector (BTEMP is not used).

Figure 4: BL-5C Battery

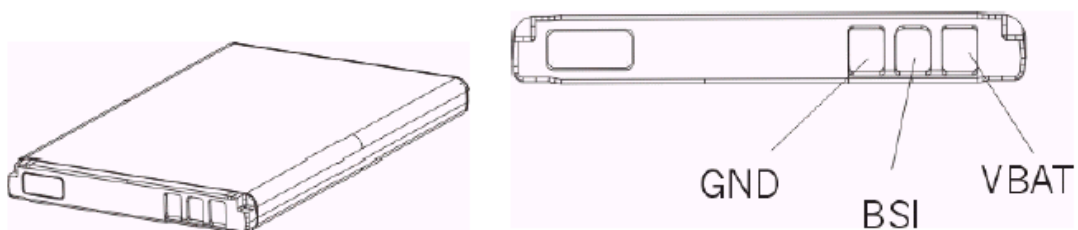


Table 3: BSI Levels BL-5C Battery

Mode	BSI (kOhm /			Description
	Min	Type	Max	
Normal		75		Used for calculating the Capacity (BL5-C = 850mA)
Service	3.2	3.3	3.4	Pull-down resistor in battery. Used for fast power-up in production (LOCAL mode), R/D purposes or in aftersales, 1% tolerance resistors shall be used.
Test	6.7	6.8	6.9	Pull-down resistor in battery, used in production for testing purposes. 1% tolerance resistors shall be used.
Banned			<3.2	

Inside the battery, an over-temperature and an over-voltage protection circuit are implemented.

Care should be taken with the temperature. If the battery is charged above 60 degrees Celsius, overheating might occur.

## Interfaces

### FM-Radio

The FM radio circuitry is implemented using a highly integrated radio IC, TEA5767HN. The MCU SW controls the FM radio circuitry through serial bus interface.

The stereo output is fed to the UEME on one of the microphone inputs.

The antenna of the FM Radio is created with the headset. The wires of the headset are used as poles of the antenna.

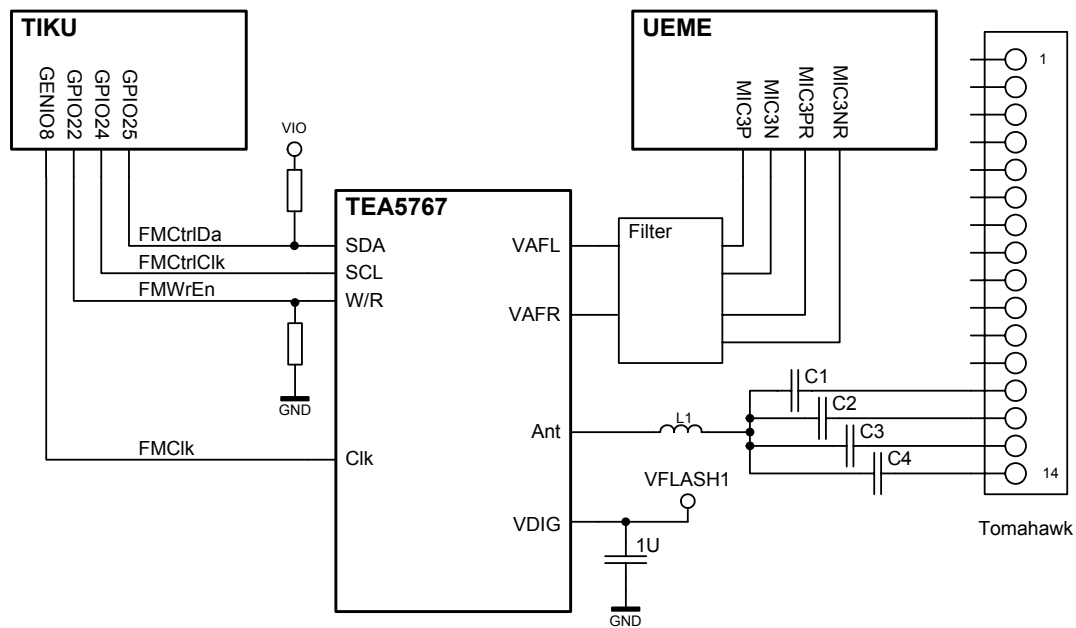
Only version TEA5767HN-VF1 and newer can be used. The previous versions have a 2.78V digital interface and need level shifters.

While W/R (WRITE/READ) is HIGH the TIKU can transmit data to the TEA5767. At the rising edge of the Bus clock, the register shifts and accepts the stable bit. At clock low the TIKU writes the following bit. A tuning function is started when the W/R signal changes from HIGH to LOW. Was a search tuning requested sent, the IC autonomously starts searching the FM band. Search direction and search stop level can be chosen. Was a station with a fieldstrength equal or higher than this stop level found, the tuning system stops and the Found Flag bit is set to "HIGH". Was during search a band limit reached, the tuning system stops at the band limit and the Band Limit flag bit is set to high. Also the Found Flag is set to high in this case.

While Write/Read is "LOW" the Tiku EDGE can read data. At the rising edge of the BUS Clock, data will be shifted out of the register. This data is available from the point where the bus clock is HIGH until the next rising edge of the clock occurs.

Interface to Engine

Figure 5: FM Radio schematic



IrDA

The RH-12/RH-28 phone supports data connectivity via the Infra Red link. The IR interface is integrated into the TIKU and the main external component is the IR module. The datarate supported will be 1.152Mbit.

Interface to Engine

This interface receives data from and transmits data to peripheral equipment. It transforms serial data to parallel data for the MCU or DSP and vice versa. The IAcIF IR interface is divided into two blocks, MIR and FIR. IR is a UART-based block for baud rates in the range 9600 bit/s to 115.2 kbit/s, and FIR is for the 1.152 Mbit/s rate. Both parts have the same physical connections so they cannot be used simultaneously. The shut down pin SD can power off the module.

The maximum distance in the RH-12/RH-28 phone configuration is approximately 20 centimetres.

The SIR block (9600 bit/s to 115.2 kbit/s):

- Supports IrDA format with speeds up to 115.2 kbit/s
- Supports Phonet format, having all the same baud rates (9600 bit/s – 115.2kbit/s) as Fbus.

The FIR block (1.152 Mbit/s):

- Supports IrDA format with baud rate 1.152 Mbit/s.
- Both these blocks are sub-divided into IR transmitter and IR receiver. Interconnection details are shown in the following figure and table.

Figure 6: IRDA Interconnections between Tiku and UEME

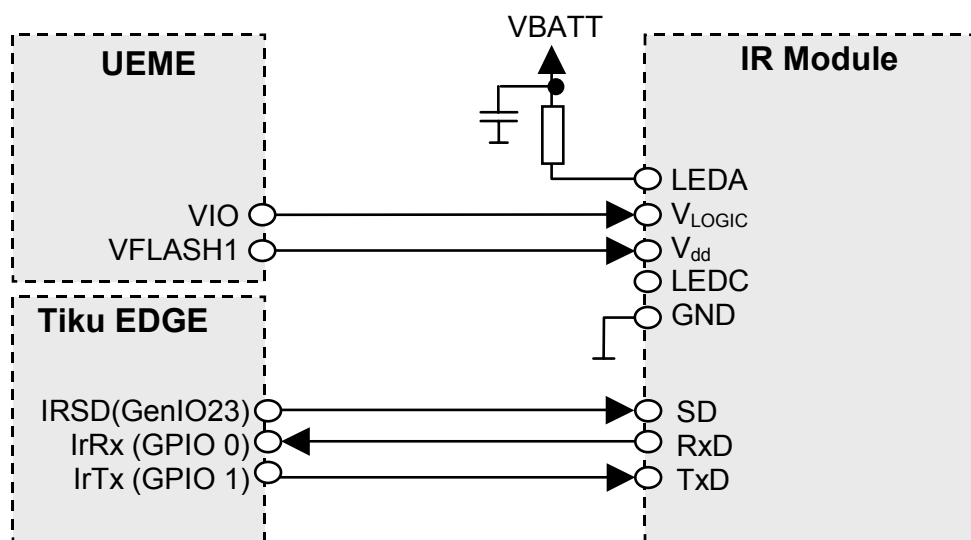


Table 4: IRDA connections between Tiku EDGE and the IR module

Name	I/O	Engine connection		Description
TXD	O	TIKU	GPIO1: [IRTx]	Transmitted data output to IR Module
RXD	I	TIKU	GPIO0: [IRRx]	Received data input from IR Module.

SD	0	TIKU	GenI023: [IRSD]	IR Module shut down.
VLOGIC	0	UEME	VIO	Supply voltage for digital parts, 1.8 V.
VCC	0	UEME	VFLASH1	IR Module supply voltage, 2.78 V.
LEDA	0	VBATT		IR LED Anode supply voltage.

**Camera**

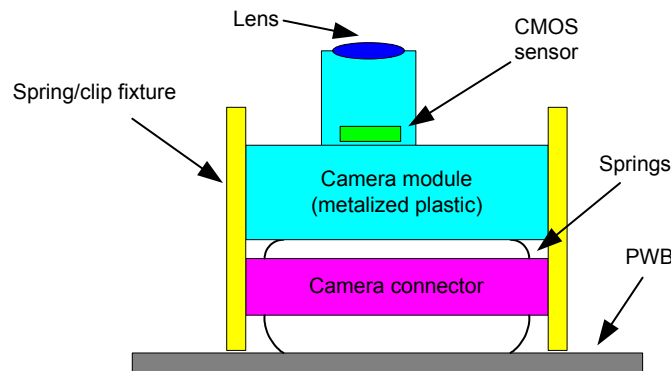
The RH-12/RH-28 phone is equipped with a VGA resolution camera with an active area of 660H x 492V. Pictures delivered to engine are standard VGA (640 x 480). This camera is able to transfer up to 30 frames per second in the viewfinder mode and 15 frames per second in full resolution mode (VGA). Full resolution pictures are in RGB 5:6:5 or YUV 4:2:2 (10 bits raw sensor resolution). The camera used is a Mirage-1 TCM8100MD module.

**Mounting**

The camera is placed physically almost inside the antenna on the backside of the phone PWB. The camera fixture (spring type, see the figure below) is located between the RF shielding cans. Shielding is done in a combination of metalized plastic housing of the camera module and ground connected spring/clip fixture.

Experience shows that good shielding is necessary. The metalized housing and the spring/clip will shield the camera. The hole for the lens is kept as small as possible to avoid direct EMC entrance into camera module by lens opening.

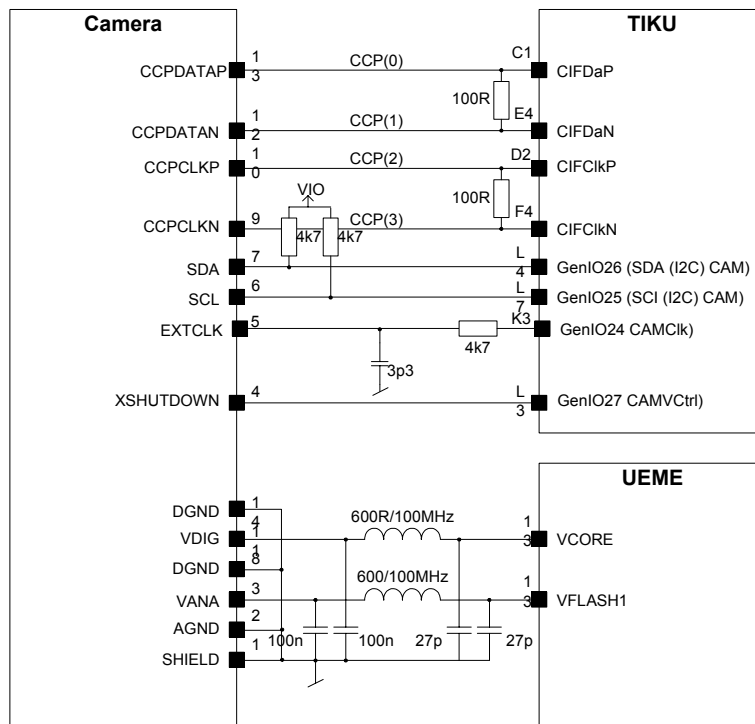
**Figure 7: Camera Module Mounting**



**Interface to Engine**

The camera is connected to the TIKU via a dedicated differential camera bus called CCP. The control of the camera is routed through normal-type general I/O ports. The camera uses 2 different supplies; analog and digital supply.

**Figure 8: Camera Interface**



Power supply to the camera module doesn't need to be shut down when the camera is in the idle mode. The camera uses very low stand-by current (1 mA in current spec).



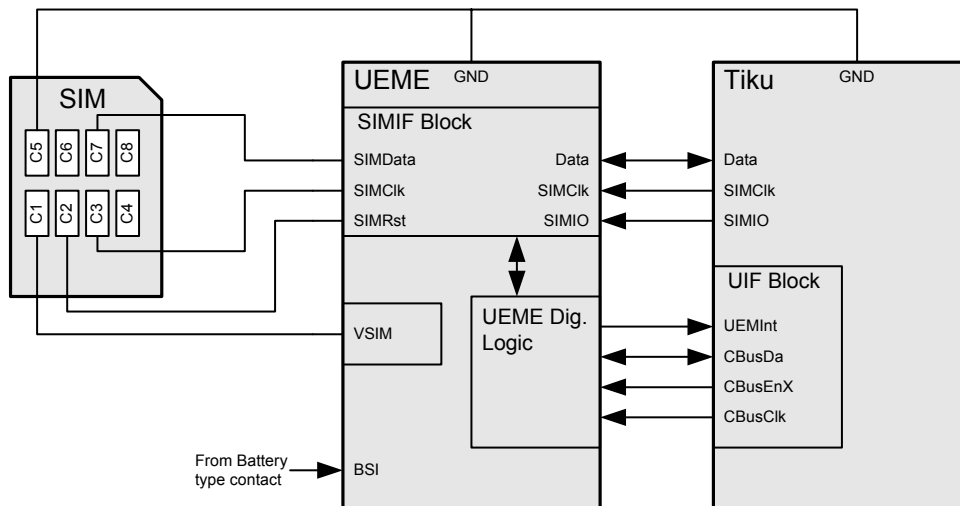
SIM

The UEME contains the SIM interface logic level shifting. The SIM interface can be programmed to support 3V and 1.8V SIMs.

The SIM interface is powered up when the SIMCardDet signal indicates, "card in". This signal is derived from the BSI signal.

Interface to Engine

Figure 9: TIKU/UEME SIM Interface Connections



The internal clock frequency from the CTSI Block is 13 MHz in GSM.

Figure 10: SIM Interface Data

Characteristics	Condition	Min	Typ	Max	Unit
SIMPwr, Vcc	on	1.6	1.8	2.0	V
		2.8	3.0	3.2	V
MoneyPwr (5 V), Icc	5 MHz	10			mA
SimPwr(3 V), Icc	4 MHz	6			mA
MoneyPwr(5V), Spikes on Icc (max duration 400 ns)	on			100	mA
SimPwr(3V), Spikes on Icc (max duration 400 ns)	on			50	mA
SimData, MoneyData, SimClk, MoneyClk, SimRst, MoneyRst, V <sub>OH</sub>		0.9 x Vcc		Vcc	V
SimData, MoneyData, V <sub>IH</sub>	(External pull-up resistor 20k to Vcc)	0.7 x Vcc		Vcc	V
SimData, MoneyData, V <sub>IL</sub>		0		0.15 x Vcc	V
SimData, MoneyData, V <sub>OL</sub>	I <sub>IL</sub> = 1 mA ***	0		0.15 x Vcc	V
SimData, MoneyData, I <sub>IH</sub>	V <sub>IH</sub>	20			μΩ
SimData, MoneyData, I <sub>OH</sub>	V <sub>OH</sub>	20			μΩ
SimData, MoneyData, I <sub>OL</sub>	V <sub>OL</sub>	20			μΩ
SimData, MoneyData, t <sub>R</sub> /t <sub>F</sub>	C <sub>IN</sub> = 30 pF; C <sub>OUT</sub> = 30 pF			1	μs
SimRst, MoneyRst	C <sub>OUT</sub> = 30 pF			1	μs
SIMCLK frequency		1.05		3.36	MHz
SimClk, MoneyClk, t <sub>R</sub> /t <sub>F</sub>	C <sub>OUT</sub> = 30 pF			26	ns
SimClk, MoneyClk, I <sub>OH</sub>	V <sub>OH</sub>	100			μΩ
SimClk, MoneyClk, I <sub>OL</sub>	V <sub>OL</sub>	20			μΩ
SimRst, MoneyRst, I <sub>OL</sub>	V <sub>OL</sub>	20			μΩ
SimRst, MoneyRst, I <sub>OH</sub>	V <sub>OH</sub>	150			μΩ
The voltage on Clock, Data and Rst shall remain between -0.3V and Vcc + 0.3 V .					

## MMC

The RH-12/RH-28 phone is equipped with a standard MMC card connector. The MMC card is physically placed under the battery, on top of the BB shielding can. The MMC card can be replaced when the phone is powered off, and the b-cover and battery are removed. The RH-12/RH-28 phone is able to accept all known high and dual voltage types of MMC cards. Only limitation is a maximum current withdrawal of 150 mA, where the maximum current class of MMC cards is 200mA.

Table 5: VMMC power specifications

Name	Voltage (V)			Current (mA)	Filter	Comment
	Min	Nom	Max	Max		
VMMC	2.76	2.85	2.94	150	1	

Mounting

The MMC card is mounted as shown in the figure below, seen from the backside of the phone, with the b-cover and battery removed. The MMC card slides in from the right side.

Figure 11: MMC Card Placement

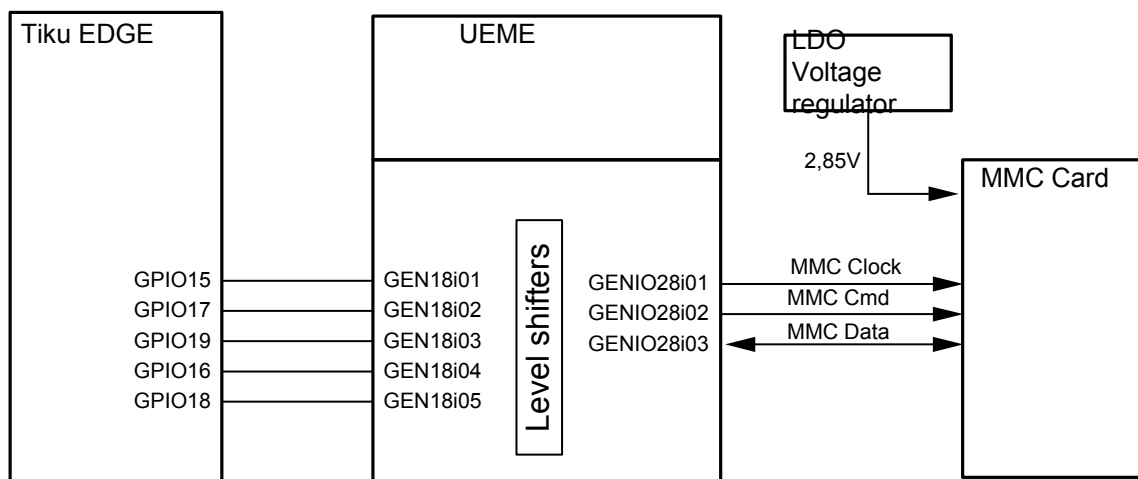


Interface to Engine

The MMC card is connected to the engine at UEME. MMC uses the dedicated MMC/secondary SIM (SWIM) card interface.

As it can be seen in the figure below, **the MMC card uses an external regulator VMMC as supply.**

Figure 12: MMC Card Engine Interface

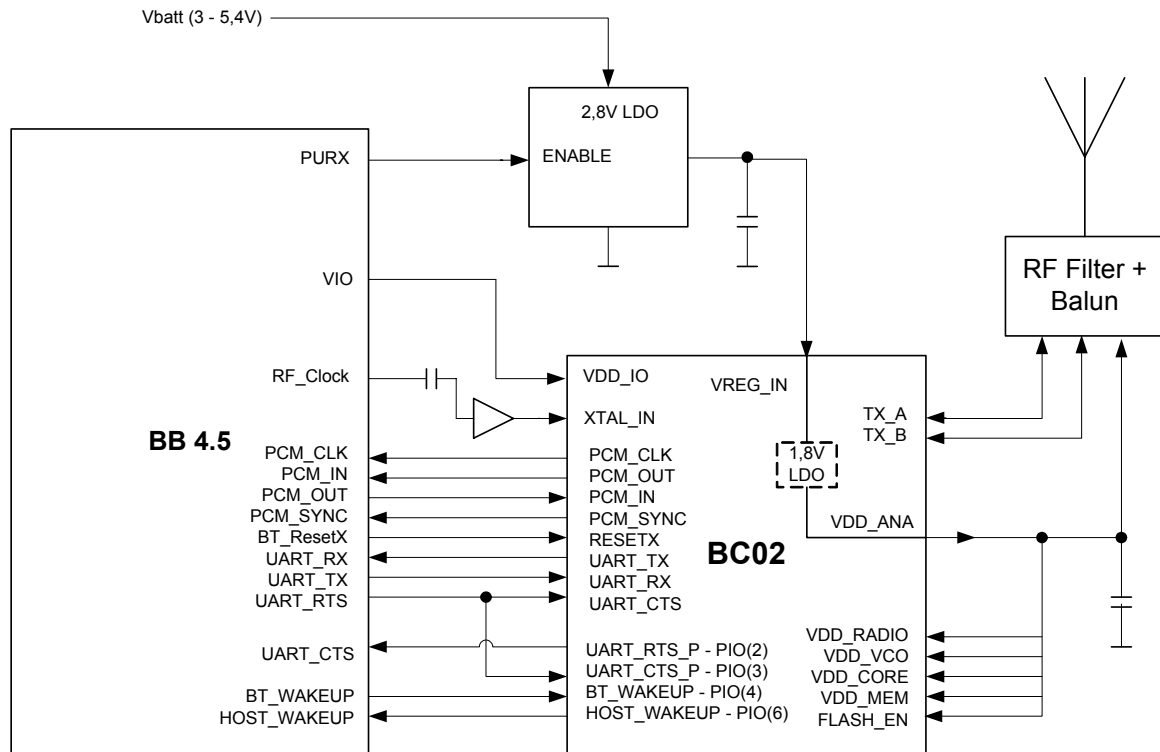


Bluetooth

The Bluetooth solution for the RH-12/RH-28 phone is a single chip solution designed by CSR.

## Interface to Engine

Figure 13: BT HW Interface



## Power Management

The external BT regulator is enabled by PURX, which is an internal UEME reset signal. This signal is high whenever the phone is powered on, which also is the case in sleep.

This means that the BC02 module power is always on. Due to this, the modules use sw power down, which results in a constant current consumption of approx. 100µA, when the BC02 module is in sleep.

## Sw Interface

Host and Bluetooth module interface can be logically divided into audio, user data and control interfaces.

User audio at 8 ksamples/s is exchanged between the host and the Bluetooth module on a PCM connection. (Optionally, the audio data can be multiplexed on a logical UART channel).

## Accessory Interface (ACI)

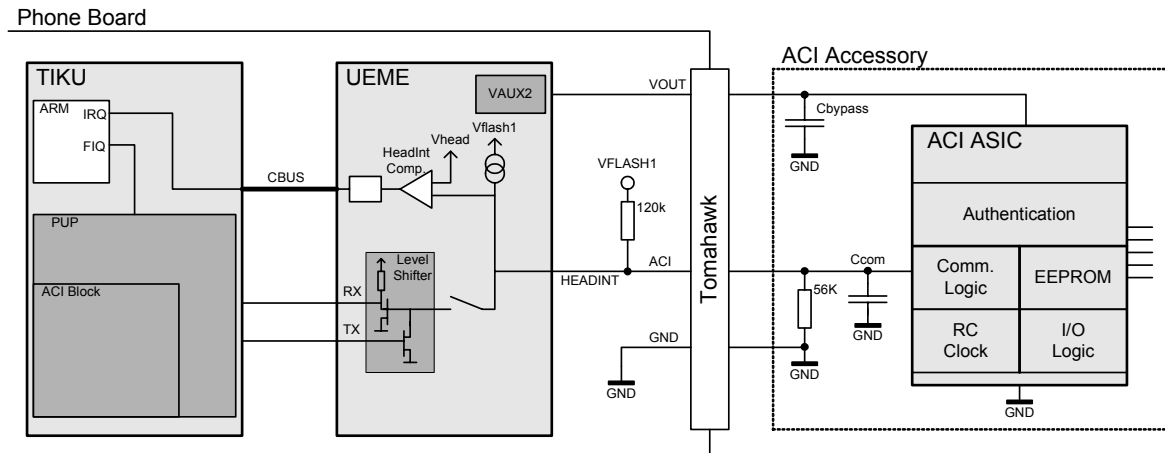
ACI (Accessory Control Interface) is a point-to-point, Master-Slave, bi-directional serial bus. ACI supports the following features:

- The identification of accessory type is provided
- The insertion and removal detection of an accessory device

- Providing power to the accessory: 200mW Power out
- Reference voltage to the accessory

The insertion / removal detection is provided by the HeadInt input.

Figure 14: ACI schematics



The Vout pin on the PopPort™ provides external power to accessories. The Vout is supplied by VAUX2 and can be controlled by the UEME. VAUX2 is short circuit protected.

Table 6: Vout specifications

Name	Voltage (V)			Current (mA)		Filter	Comment
	Min	Nom	Max	Max	Sleep Max		
VAUX2	2.70	2.78	2.86	70	0.5	1	

**FBUS**

More intelligent accessories can use the serial FBUS connection.

These devices can use Vout as the power supply and ACI for identification.

FBUS is an asynchronous data bus having separate TX and RX signals. Default bit rate of the bus is 115.2 Kbit/s. FBUS is mainly used for controlling the phone in the production and for interface to PC via serial cables. Tiku can also support fast bus. This is FBUS with a bitrate of 1.2Mbit.

Fbus is using the same pins as the USB connection.

Table 7: Fbus signals

Name	Name	Voltage (V)			Comment
		Min	Nom	Max	
FBUS RX	VIH	1.95	2.78	3.00	0.7*VFLASH1
	VIL	0	0.20	0.83	0.3*VFLASH1
FBUS TX	VOH	1.95	2.78	3.00	0.7*VFLASH1
	VOL	0	0.20	0.83	0.3*VFLASH1
Rise Time				12.5ns	For Rx and Tx signals

## USB

The Nokia USB device solution is supported using the Wireless 2 Function Controller (W2FC) core. This core is included in the TIKU ASIC. The core completes several USB functions automatically and is controlled by the ARM9 MCU.

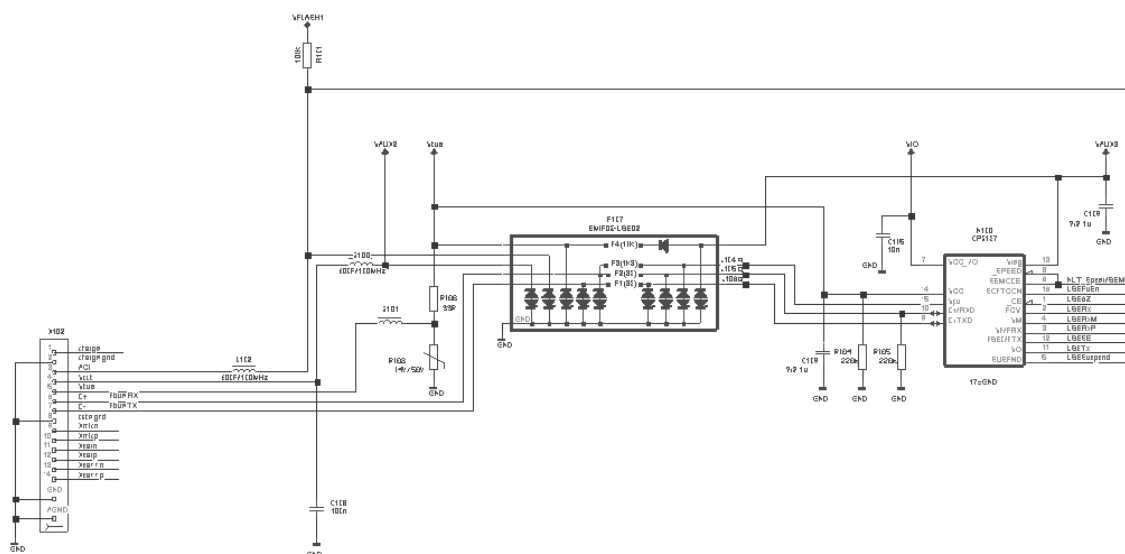
NUT provides the interface between the ASIC's 1.8 V bus and the 3.3 V USB bus. In addition, NUT is capable of transmitting and receiving Fbus signals to and from the Fbus UART in Tiku.

Nokia USB Transceiver (NUT) is fully compliant with the Universal Serial Bus Specification Rev. 1.1.

NUT is able to transmit and receive serial data at full-speed (12 Mbit/s).

The USB signal ESD protection and line matching resistance, and USB pull-up resistor is included to the USB ASIP. This component also includes ESD protection for VOUT and ACI system connector pins.

Figure 15: USB Circuit



## UI Interface

### Display Unit

Hardware Interface:

The Display Unit interface is a parallel interface consisting of the following:

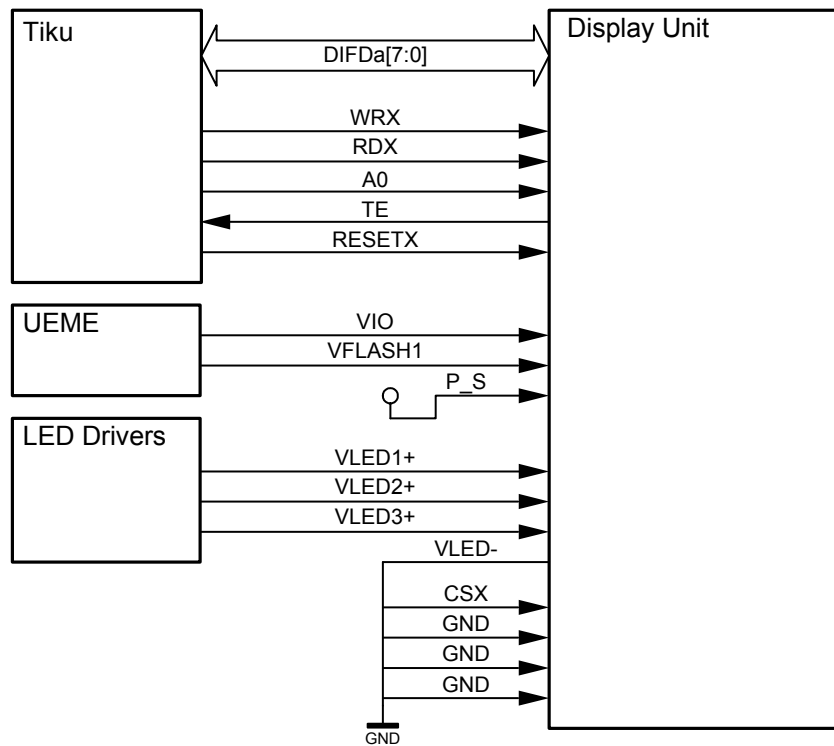
- 8-bit data bus (DISPDATA(7:0))
- Write enable WRX
- Read enable RDX

A 24-pin connector as shown in the figure below provides the interface between the Display Unit and the Engine PWB.

Internally, the TIKU DIF block has interfaces with the VIA bus and the secondary DMA controller.

Interconnection details are shown in the figure below.

Figure 16: Display Unit Connections



### Keyboard and Navigator

The RH-12/RH-28 phone consists of a mainboard with interface to the UI board. The connection between the main board and the UI board is via a board-to-board connector.

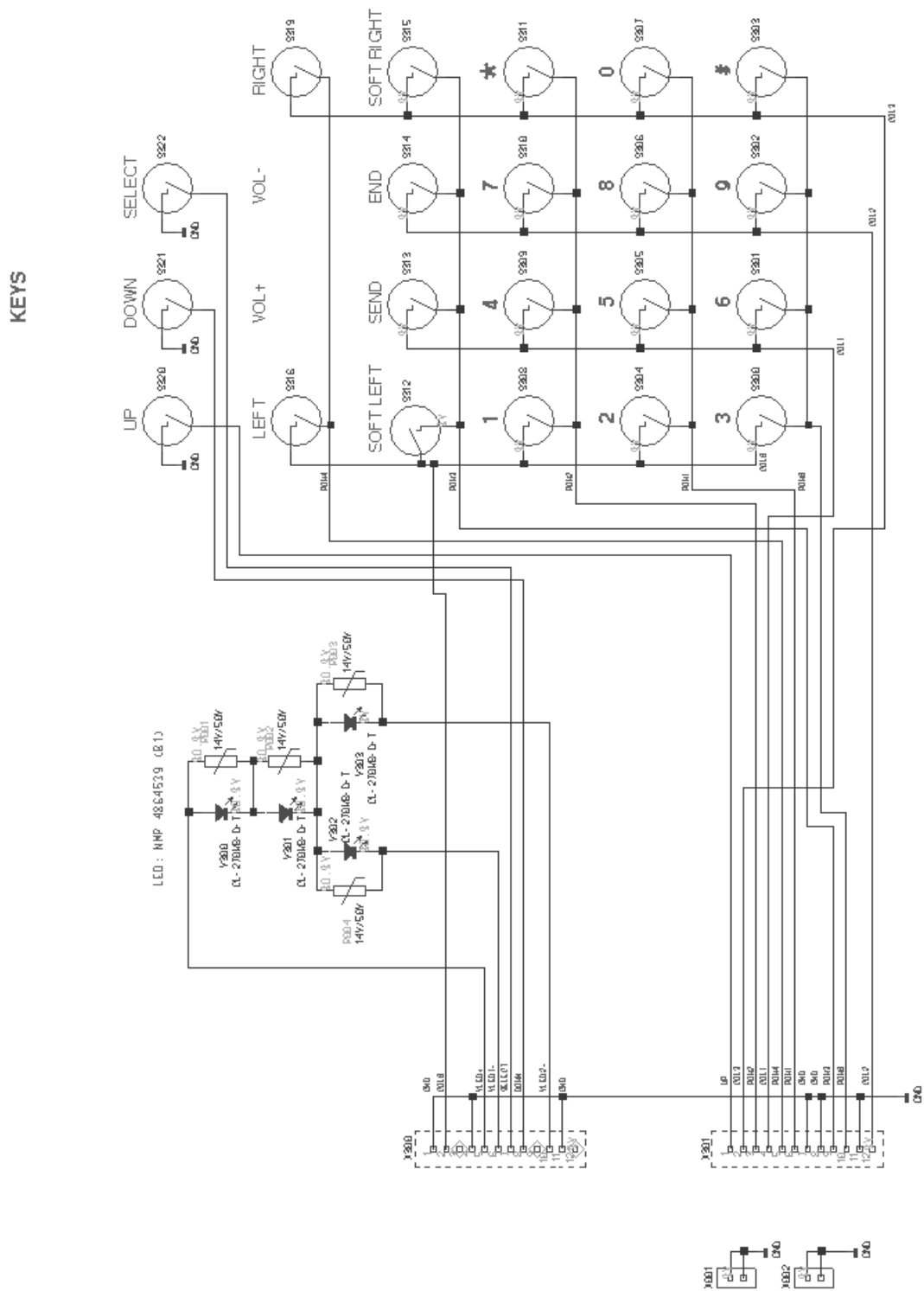
The signals on the board-to-board connector are:

- Signals for LED's
- Signals for numeric Keypad and navigation key

The UI board is the base for the keyboard, which includes a five-way navigation key.



Figure 17: Keyboard layout with special keys for Navi\_Up, Navi\_Down and Navi\_Select



**Table 8: Keyboard allocation Tiku GPIO**

Keypad matrix and Navigation key		Tiku connection		Description
Navigation Key	Left	Tiku	-	Separate controllines (Special keys) for Navi_Up, Navi_Down and Navi_Select. Navi_Left and Navi_Right are connected to the keyboard matrix
	Up		GPIO 6	
	Right		-	
	Down		GPIO 7	
	Select		GPIO 13	
	GND		-	
Keypad	Column 0	Tiku	GPIO 2	Tiku, Keyboard interface KDI in the UIF block,
	Column 1		GPIO 3	
	Column 2		GPIO 4	
	Column 3		GPIO 5	
	Row 0		GPIO 8	
	Row 1		GPIO 9	
	Row 2		GPIO 10	
	Row 3		GPIO 11	
	Row 4		GPIO 12	

**Multiple-keypress:**

The RH-12/RH-28 phone will implement multiple keypress. By multiple keypress we mean the ability to detect that the user has pressed several keys simultaneously. The incitement for implementing this functionality is mainly the support for Java and the requirements set by games.

UI software is capable of supporting multiple keypress, while core SW will have to incorporate this feature into the keyboard driver.

With the current implementation, the design supports 2 simultaneously arbitrarily pressed keys in the keyboard matrix, together with any combination of Navi\_Up, Navi\_Select and Navi\_Down (The special keys).

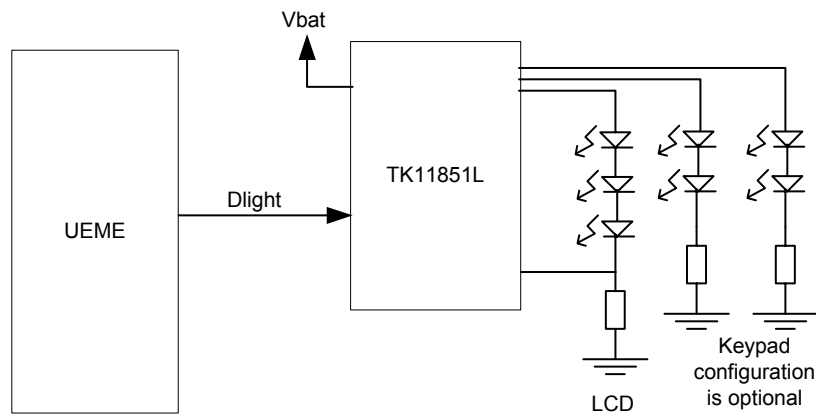
**LED Driver**

The RH-12/RH-28 phone UI module has 2 sets of LED's:

- 3 pcs. for LCD – LED: White
- 2 pcs. for Keyboard (prepared for 4) – LED: White, sidefiring

Both groups are individual controllable by the PWM output signal from UEME ASICs

Figure 18: . LED driver block



#### Intensity Control:

LEDs are controlled by the PWM output from UEME UI block. The PWM controls can be adjusted in 8-bit step (256). The TK11851L contains a sleep mode. This mode is achieved when the Dlight signal is low.

#### Vibra

A vibra-alerting device is used to generate a vibration signal for an incoming call. The vibra is placed in the top of the phone. It is placed in the D-cover next to the microphone.

The vibra is electrically connected to the PWB by spring contacts.

The vibra is controlled from the UEME by a PWM (Pulse Wide Modulated) square wave signal.

#### IHF-speaker

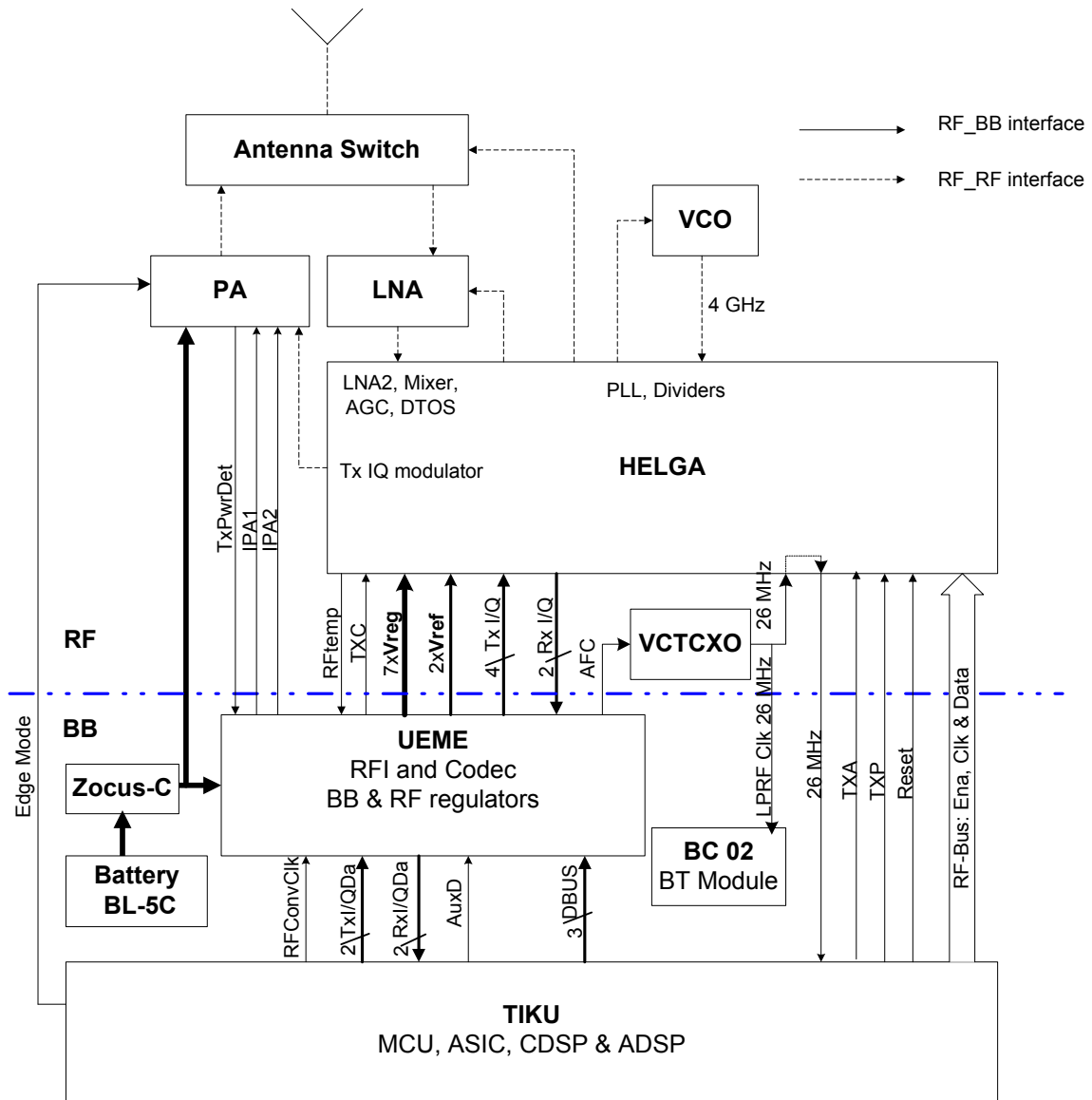
Alerting tones and/or melodies are generated by an Internal HandsFree speaker, which is controlled by a PWM signal from the UEME.

The ringer melodies will be optimised in MCU so the main frequency of any given melody is shifted to near the resonant peak. Sound hole is placed in the D-cover The IHF is electrically connected to the PWB by spring contacts.

## RF Interface

The interface between baseband and the RF section is shown below:

Figure 19: Simplified RF/BB Interface Block Diagram



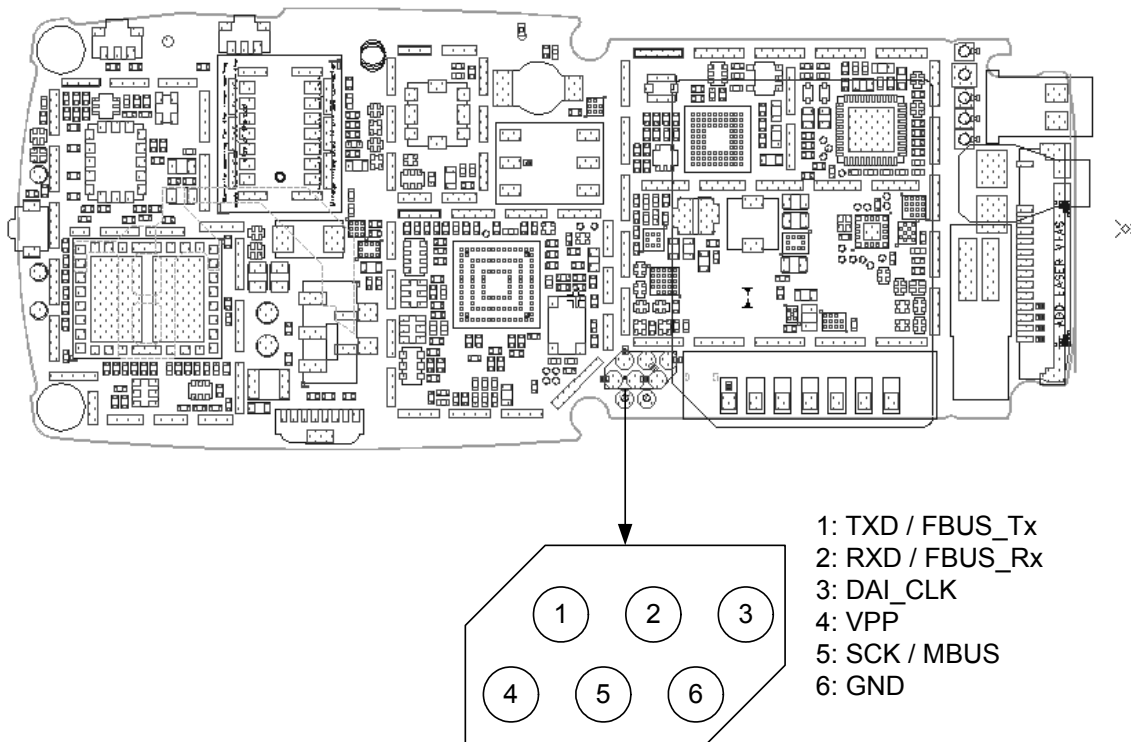
## Test Pattern

Test pads are placed on engine PWB for service.

RH-12/RH-28 has adopted the two-row test pattern layout. The basic test pads (FBUS\_TX, FBUS\_RX, VPP, MBUS & GND) have a defined location, while optional signals can be on either side of the test pads. The 'DAI\_CLK' is included as an optional signal.

For specific test pad placement, please see the figure below.

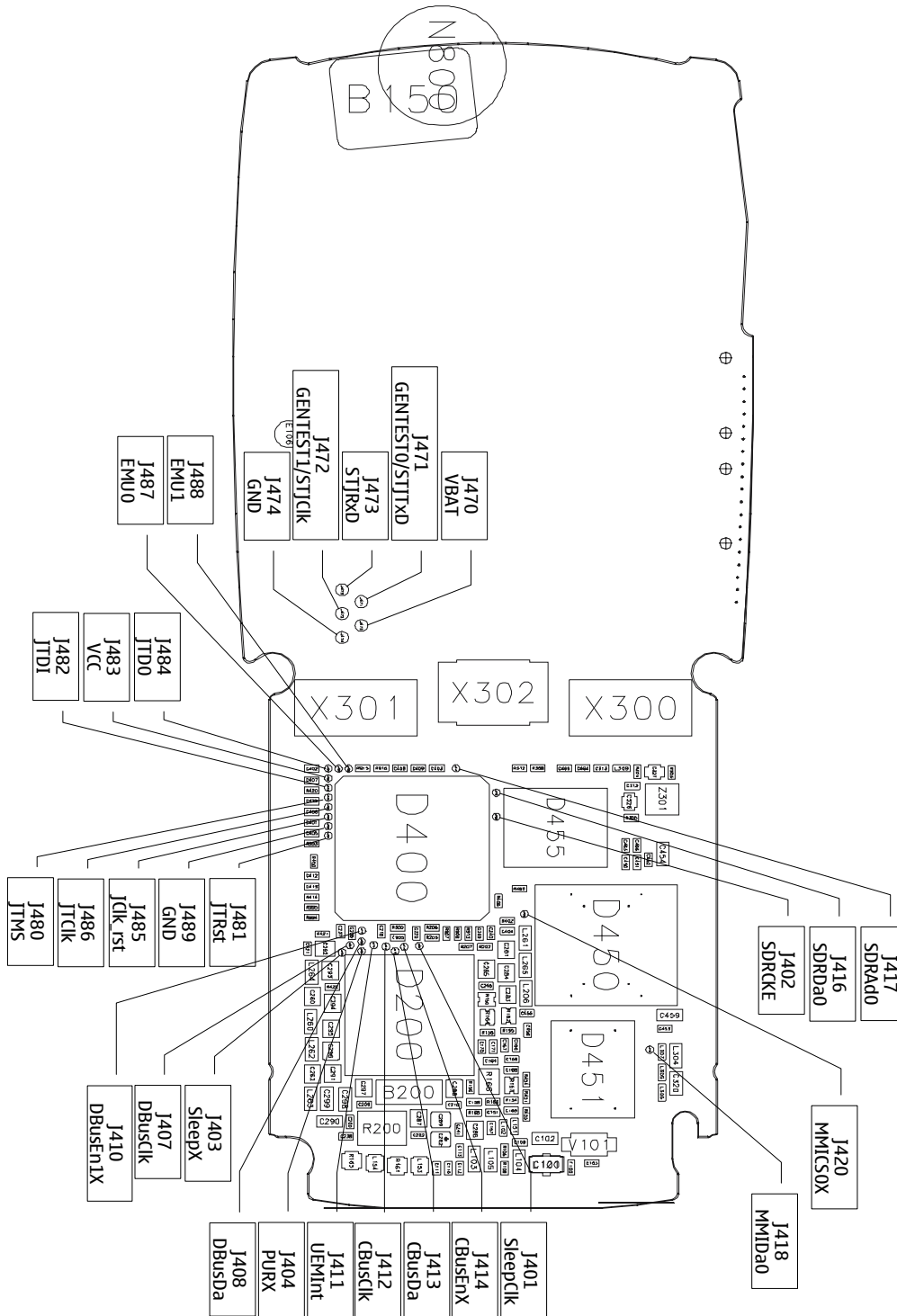
Figure 20: Production Test Pattern



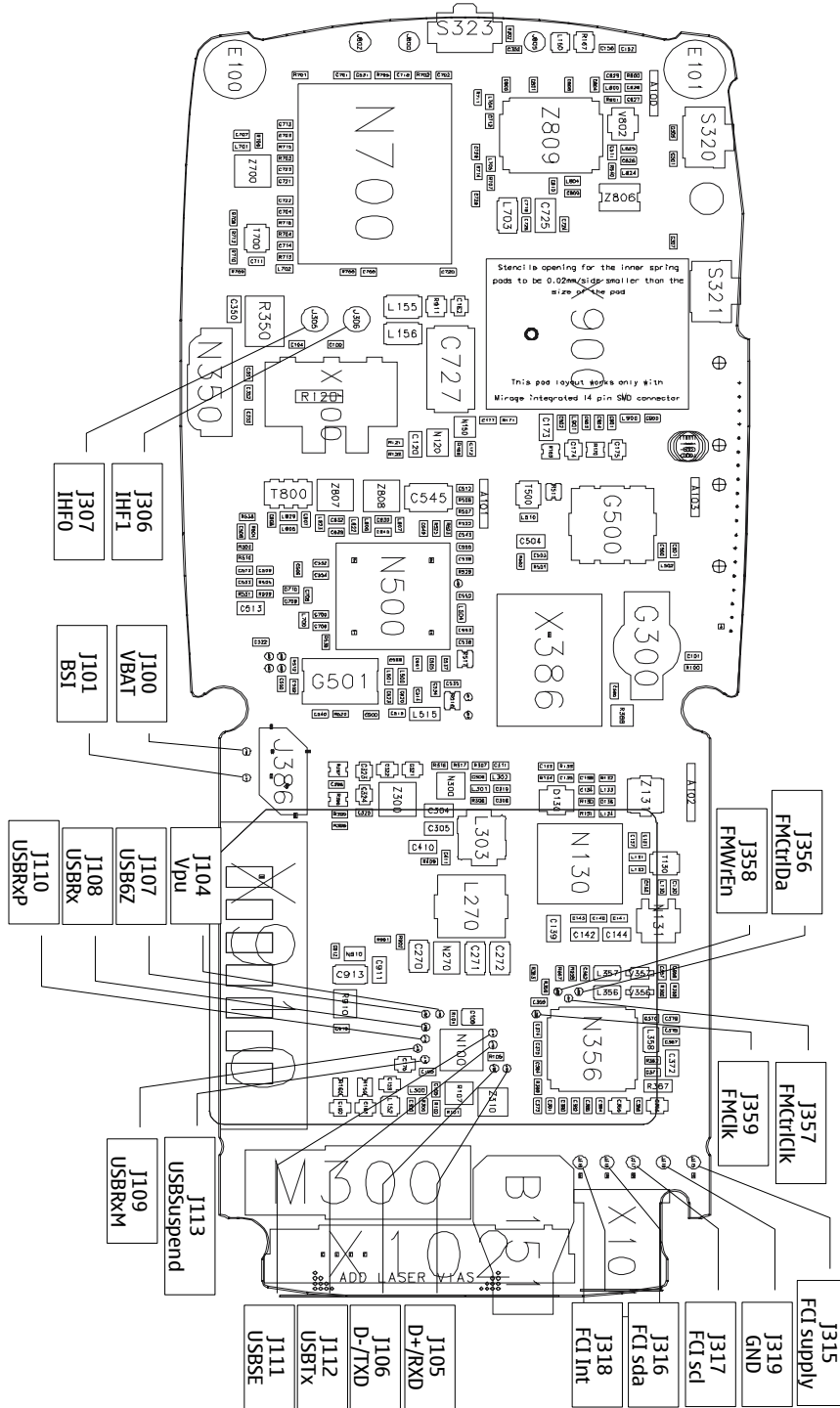
## Test Points

See the following two figures for an indication as to where some of the test points can be found.

### Main board A side of PWB



Main board B side of PWB



## RF Module Introduction

The RF module performs the necessary high frequency operations of the EGSM900/GSM1800/GSM1900 triple band (EDGE) engine in the RH-12/RH-28 product. The EGSM900 is rematched to GSM850 in the RH-28 product.

Both, the transmitter and receiver have been implemented by using direct conversion architecture, which means that the modulator and demodulator operate at the channel frequency.

The core of the RF is an application-specific integrated circuit, Helgo. Another core component is a power amplifier module, which includes two amplifier chains, one for GSM850/EGSM900 and the other for GSM1800/GSM1900.

Other key components include:

- 26 MHz VCTCXO for frequency reference
- 3296–3980 MHz SHF VCO (super high frequency voltage controlled oscillator)
- front end module comprising a RX/TX switch and two RF bandpass SAW filters
- three additional SAW filters

The control information for the RF is coming from the baseband section of the engine through a serial bus, referred later on as RFBus. This serial bus is used to pass the information about the frequency band, mode of operation, and synthesizer channel for the RF.

In addition, exact timing information and receiver gain settings are transferred through the RFBus. Physically, the bus is located between the baseband ASIC called UPP and Helgo. Using the information obtained from UPP, Helgo controls itself to the required mode of operation and further sends control signals to the front end and power amplifier modules. In addition to the RFBus, there are still other interface signals for the power control loop and VCTCXO control and for the modulated waveforms.

The RF circuitry is located on the top side of the 8 layer PWB.

EMC leakage is prevented by using a metal cans. The RF circuits are separated to three blocks:

- FM radio
- PA, front end module, LNA and 1900 band SAWs
- Helgo RF IC, VCO, VCTCXO, baluns and balanced filters

The RF transmission lines constitute of striplines and microstriplines after PA.

The baseband circuitry is located on the one side of the board, which is shielded with a

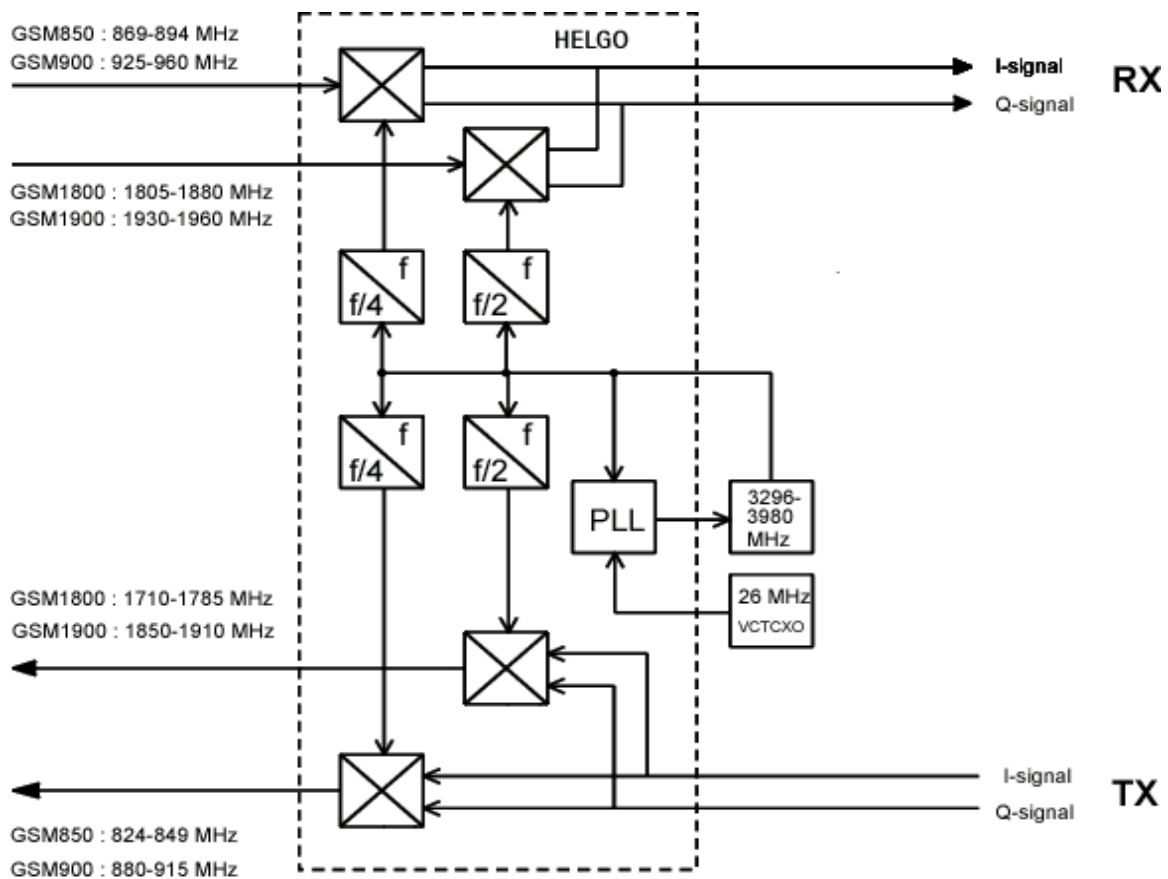


meallized frame and ground plane of the UI-board.

### RF Frequency Plan

RF frequency plan is shown below. The VCO operates at the channel frequency multiplied by two or four, depending on the frequency band of operation. This means that the baseband-modulated signals are directly converted up to the transmission frequency and the received RF signals directly down to the baseband frequency.

Figure 21: RF Frequency Plan



### DC Characteristics

#### Regulators

The transceiver baseband section has a multi-function analog ASIC, UEM, which contains among other functions six pieces of 2.78 V linear regulators and a 4.8 V switching regulator.

All regulators can be controlled individually by the 2.78 V logic directly or through a control register.

The use of the regulators can be seen in the power distribution diagram, which is presented in the Figure Power Distribution Diagram below.

The seven regulators are named VR1 to VR7. VrefRF01 and VrefRF02 are used as the reference voltages for the Helgo, VrefRF01 (1.35V) for the bias reference and VrefRF02 (1.35V) for the RX ADC (analog-to-digital converter) reference.

The regulators (except for VR7) are connected to the Helgo. Different modes of operation can be selected inside the Helgo according to the control information coming through the RFBus.

**Table 9: List of the needed supply voltages**

Volt. Source	Load
VR1	PLL charge pump (4.8 V)
VR2	TX modulators, VPECTRL3s (ALC), driver
VR3	VCTCXO, synthesizer digital parts
VR4	Helgo pre-amps, mixers, DtoS
VR5	dividers, LO-buffers, prescaler
VR6	LNAs, Helgo baseband (Vdd_bb)
VR7	VCO
VrefRF01	ref. Voltage for Helgo
VrefRF02	ref. Voltage for Helgo
Vbatt	PA

### Typical Current Consumption

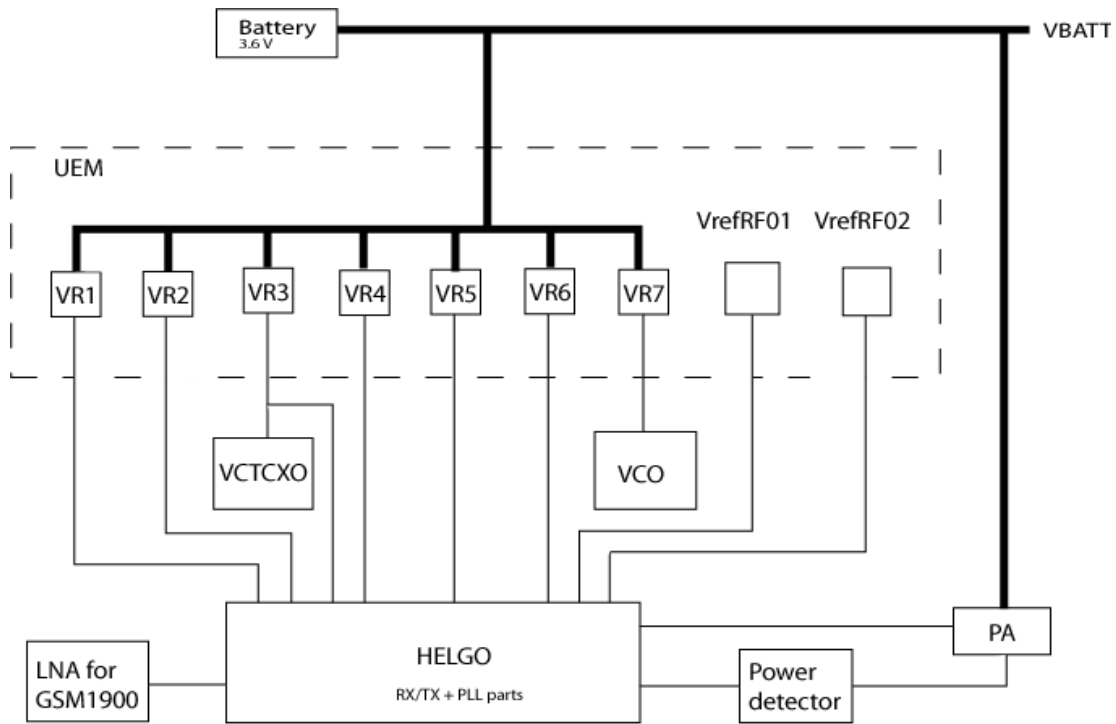
The table below shows the typical current consumption in different operation modes.

**Table 10: Typical current consumption in different operation modes**

Operation mode	Current consumption	Notes
Power OFF	< 10 uA	Leakage current (triple band PA)
RX, EGSM900	75 mA, peak	
RX, GSM1800/GSM1900	70 mA, peak	
TX, power level 5, EGSM900	1700 mA, peak	
TX, power level 0, GSM1800/GSM1900	1000 mA, peak	

Power Distribution

Figure 22: Power Distribution Diagram



RF Characteristics

Table 11: Channel Numbers and Frequencies

System	Channel number	TX frequency	RX frequency	Unit
GSM850	$128 \leq n \leq 251$	$F = 824.2 + 0.2 * (n - 128)$	$F = 869.2 + 0.2 * (n - 128)$	MHz
GSM900	$0 < n \leq 124$	$F = 890 + 0.2 * n$	$F = 935 + 0.2 * n$	MHz
	$975 \leq n \leq 1023$	$F = 890 + 0.2 * (n - 1024)$	$F = 935 + 0.2 * (n - 1024)$	MHz
GSM1800	$512 \leq n \leq 885$	$F = 1710.2 + 0.2 * (n - 512)$	$F = 1805.2 + 0.2 * (n - 512)$	MHz
GSM1900	$512 \leq n \leq 810$	$F = 1850.2 + 0.2 * (n - 512)$	$F = 1930.2 + 0.2 * (n - 512)$	MHz

Table 12: Main RF Characteristics

Parameter	Unit and value
Cellular system[RH-12] [RH-28]	EGSM900/GSM1800/GSM1900 GSM850/GSM1800/GSM1900
RX Frequency range	GSM850: 869 ... 894 MHz EGSM900: 925 ... 960 MHz GSM1800: 1805...1880 MHz GSM1900: 1930...1990 MHz
TX Frequency range	GSM850: 824 ... 849 MHz EGSM900: 880 ... 915 MHz GSM1800: 1710 ...1785 MHz GSM1900: 1850 ...1910 MHz
Duplex spacing	GSM850: 45 MHz EGSM900: 45 MHz GSM1800: 95 MHz GSM1900: 80 MHz
Channel spacing	200 kHz
Number of RF channels	GSM850: 124 EGSM900: 174 GSM1800: 374 GSM1900: 300
Output Power	GSM850: GSMK 5...33 dBm GSM850: 8-PSK 5...27 dBm EGSM900: GSMK 5...33 dBm EGSM900: 8-PSK 5...27 dBm GSM1800: GSMK 0...30 dBm GSM1800: 8-PSK 0...26 dBm GSM1900: GSMK 0...30 dBm GSM1900: 8-PSK 0...26 dBm
Number of power levels GSMK	GSM850: 15 EGSM900: 15 GSM1800: 16 GSM1900: 16
Number of power levels 8-PSK	GSM850: 12 EGSM900: 12 GSM1800: 14 GSM1900: 14

**Table 13: Transmitter Characteristics**

Item	Values (EGSM900/1800/1900)
Type	Direct conversion, nonlinear, FDMA/TDMA
LO frequency range	GSM850: 3296...3395 MHz (4 x TX freq) EGSM900: 3520...3660 MHz (4 x TX freq) GSM1800: 3420...3570 MHz (2 x TX freq) GSM1900: 3700...3820 MHz (2 x TX freq)
Output power (GSM850/EGSM900/GSM1800/GSM1900)	GMSK 33/33/30/30 dBm 8-PSK 27/27/26/26 dBm

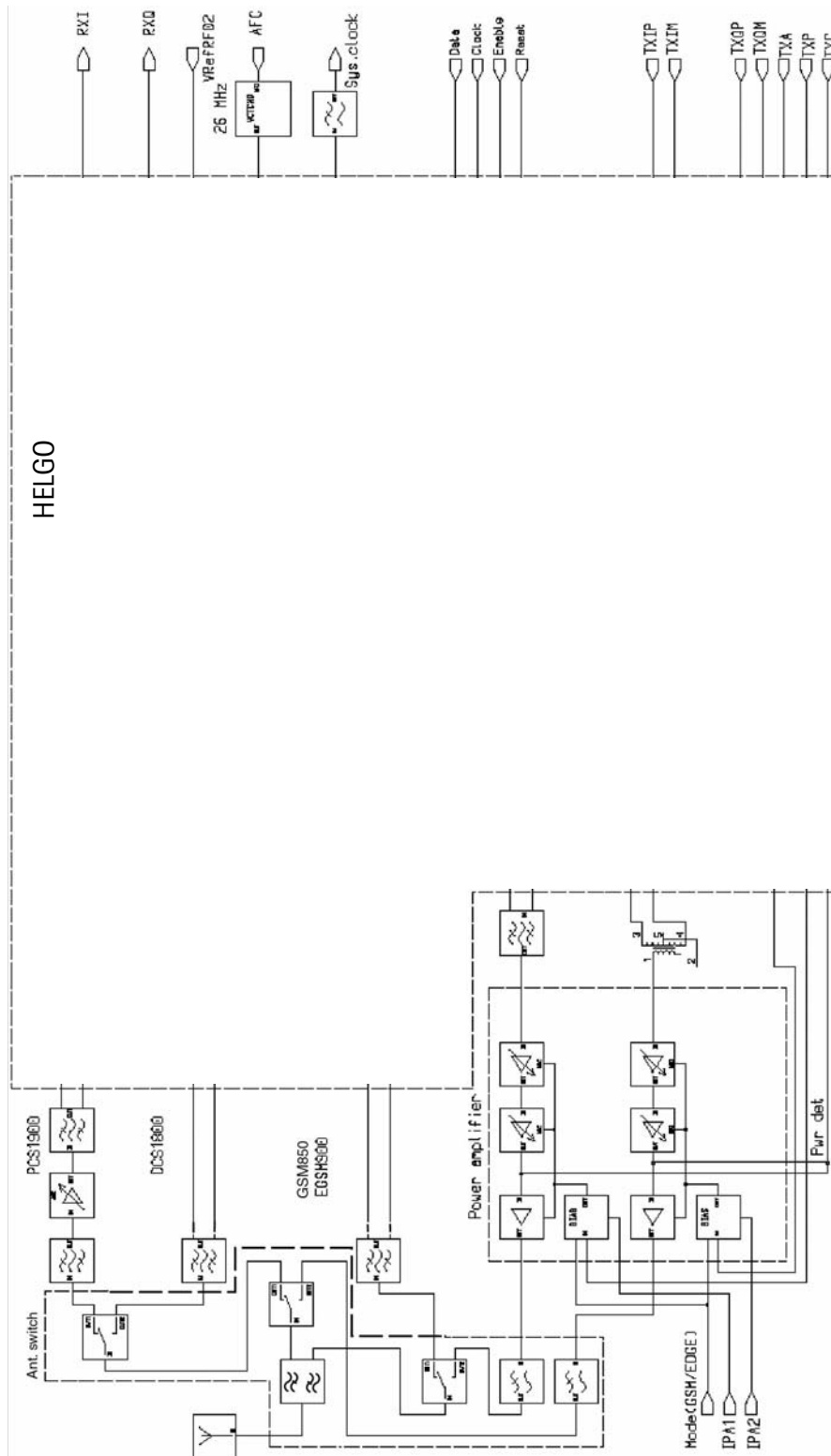
**Table 14: Receiver Characteristics**

Item	Values, EGSM900/1800/1900
Type	Direct conversion, Linear, FDMA/TDMA
LO frequencies	GSM850: 3476...3575 MHz (4 x RX freq) EGSM900: 3700...3840 MHz (4 x RX freq) GSM1800: 3610...3760 MHz (2 x RX freq) GSM1900: 3860...3980 MHz (2 x RX freq)
Typical 3 dB bandwidth	+/- 91 kHz
Sensitivity	min. - 102 dBm (normal condition)
Total typical receiver voltage gain (from antenna to RX ADC)	86 dB
Receiver output level (RF level -95 dBm)	230 mVpp, single-ended I/Q signals to RX ADCs

## RF Block Diagram

The block diagram of the RF module can be seen in the following figure. The detailed functional description is given in the following sections.

Figure 23: RF Block Diagram



## Frequency Synthesizers

The VCO frequency is locked by a PLL (phase locked loop) into a stable frequency source given by a VCTCXO, which is running at 26 MHz. The frequency of the VCTCXO is in turn locked into the frequency of the base station with the help of an AFC voltage, which is generated in UEM by an 11 bit D/A converter. The PLL is located in Helgo and it is controlled through the RFBus.

The required frequency dividers for modulator and demodulator mixers are integrated in Helgo.

The loop filter filters out the comparison pulses of the phase detector and generates a DC control voltage to the VCO. The loop filter determines the step response of the PLL (settling time) and contributes to the stability of the loop.

The frequency synthesizer is integrated in Helgo except for the VCTCXO, VCO, and the loop filter.

## Receiver

Each receiver path is a direct conversion linear receiver. From the antenna the received RF signal is fed to a front-end module where a diplexer first divides the signal to two separate paths according to the band of operation: either lower, GSM850/EGSM900 or upper, GSM1800/GSM1900 path.

Most of the receiver circuitry is included in Helgo.

## Transmitter

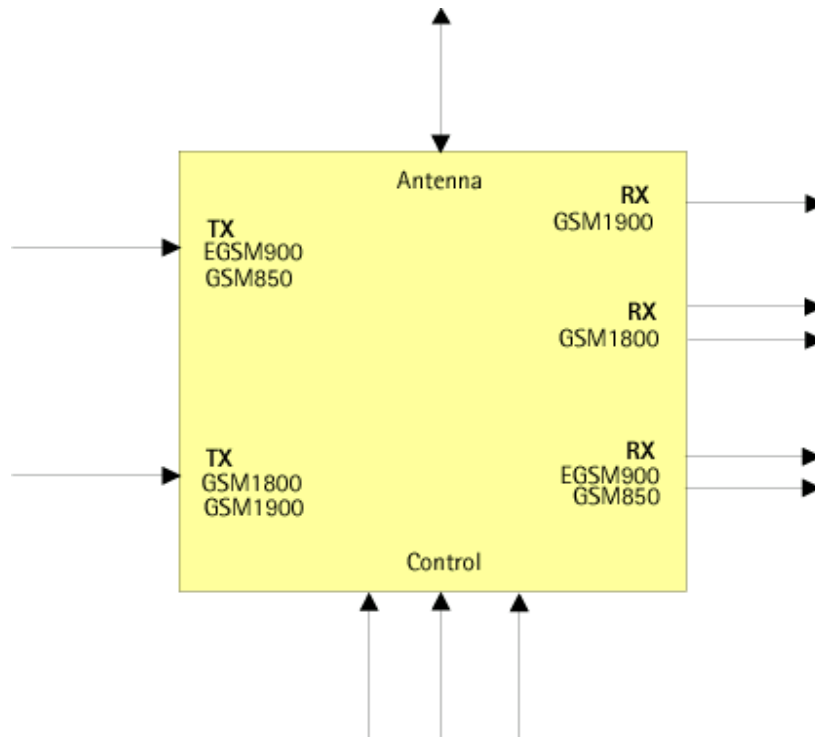
The transmitter consists of two final frequency IQ-modulators and power amplifiers, for the lower and upper bands separately, and a power control loop. The IQ-modulators are integrated in Helgo, as well as the operational amplifiers of the power control loop. The two power amplifiers are located in a single module with power detector. In the GMSK mode the power is controlled by adjusting the DC bias levels of the power amplifiers.

## Front End

The front end features include:

- Antenna 50 ohm input
- RX GSM850/EGSM900 balanced output
- RX GSM1800 balanced output
- RX GSM1900 single ended output
- TX GSM850/GSM900 single ended 50 ohm input
- TX GSM1800/GSM1900 single ended 50 ohm input
- 3 control lines from the Helgo

Figure 24: Front End

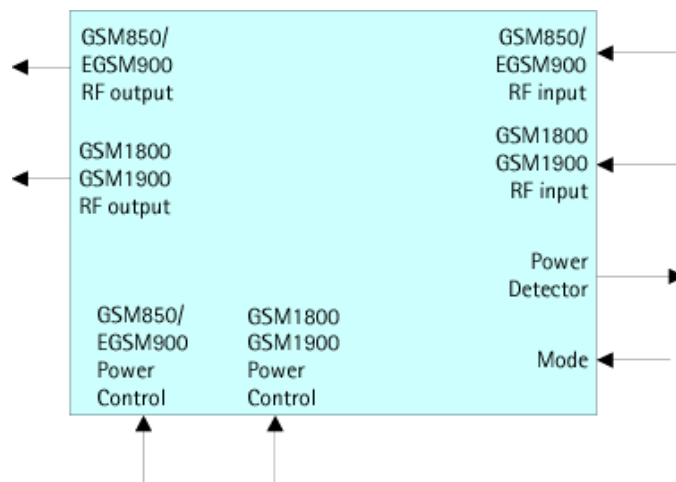


**Power Amplifier**

The power amplifier features include:

- 50 ohm input and output, GSM850/EGSM900 and GSM1800/GSM1900
- Internal power detector
- GMSK and EDGE mode

Figure 25: Power Amplifier





## RF ASIC Helgo

The RF ASIC features include

- Package uBGA108
- Balanced I/Q demodulator and balanced I/Q modulator
- Power control operational amplifier, acts as an error amplifier
- The signal from VCO is balanced, frequencies 3296 to 3980 MHz
- Low noise amplifiers (LNAs) for GSM850/EGSM900 and GSM1800 are integrated

The Helgo can be tested by test points only.

## AFC function

AFC is used to lock the transceiver's clock to the frequency of the base station.

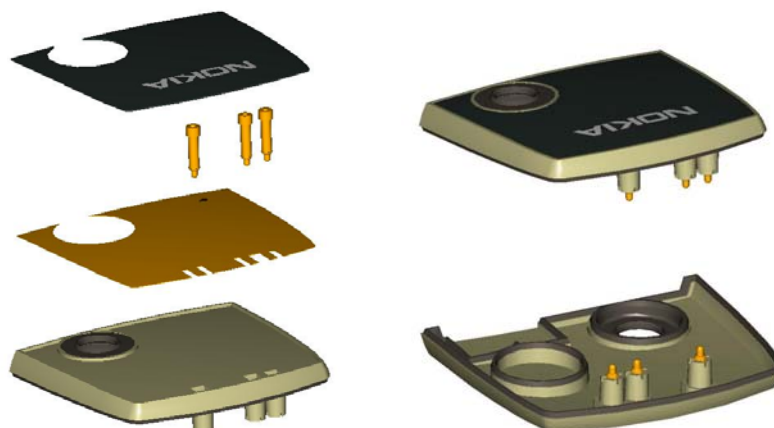
## Antenna

The antenna for RH-12/RH-28 is a triple band antenna.

Two versions:

- RH-12 GSM900/GSM1800/GSM1900
- RH-28 GSM850/GSM1800/GSM1900

Antenna concept: Flex print on substrate covered with decorated label



The antenna also works as cover for the IHF-speaker (Internal Handsfree Speaker). The IHF sound chamber and the camera are sealed with a rubber gasket (part of the antenna).

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